

2.3 (Continued)

$$\frac{d^2 y}{dt^2} + p \frac{dy}{dt} + q y = 0$$

$$\text{Try } y(t) = e^{st} \Rightarrow s^2 + ps + q = 0$$

$$s = \frac{-p \pm \sqrt{p^2 - 4q}}{2}$$

$$\text{Case 3: } p^2 - 4q = 0$$

$$\Rightarrow s = -\frac{p}{2} \quad y_1(t) = e^{-\frac{p}{2}t} \text{ is a particular sol'n.}$$

$$\text{Fact: } y_2(t) = t e^{-\frac{p}{2}t} \text{ is also a particular sol'n.}$$

$$\frac{dy_2}{dt} = e^{-\frac{p}{2}t} + t \cdot \left(-\frac{p}{2}\right) e^{-\frac{p}{2}t}$$

$$= e^{-\frac{p}{2}t} \left(1 - \frac{p}{2}t\right)$$

$$\frac{d^2 y_2}{dt^2} = \left(-\frac{p}{2}\right) e^{-\frac{p}{2}t} \left(1 - \frac{p}{2}t\right) + e^{-\frac{p}{2}t} \cdot \left(-\frac{p}{2}\right)$$

$$= e^{-\frac{p}{2}t} \left(-\frac{p}{2} + \frac{p^2}{4}t - \frac{p}{2}\right)$$

$$= e^{-\frac{p}{2}t} \left(-p + \frac{p^2}{4}t\right)$$

$$q = \frac{p^2}{4}$$

$$\frac{d^2 y_2}{dt^2} + p \frac{dy_2}{dt} + q y_2 = e^{-\frac{p}{2}t} \left(-p + \frac{p^2}{4}t + p\left(1 - \frac{p}{2}t\right) + \frac{p^2}{4}t\right)$$

$$= e^{-\frac{p}{2}t} \left(\cancel{-p} + \frac{p^2}{4}t + \cancel{p} - \frac{p^2}{2}t + \frac{p^2}{4}t\right) = 0$$

Summarize for $\frac{d^2 y}{dt^2} + p \frac{dy}{dt} + q y = 0$

Solve $s^2 + ps + q = 0$ "characteristic equation"

$$s = \frac{-p \pm \sqrt{p^2 - 4q}}{2}$$

Case 1: $p^2 - 4q > 0 \Rightarrow$ get particular sol'n's

$$y_1(t) = e^{s_1 t}, \quad y_2(t) = e^{s_2 t}$$

Case 2: $p^2 - 4q < 0 \Rightarrow$ get particular sol'n's

$$y_1(t) = e^{-\frac{p}{2}t} \cos\left(\frac{\sqrt{4q-p^2}}{2}t\right)$$

$$y_2(t) = e^{-\frac{p}{2}t} \sin\left(\frac{\sqrt{4q-p^2}}{2}t\right)$$

Case 3: $p^2 - 4q = 0 \Rightarrow$ get particular sol'n's

$$y_1(t) = e^{-\frac{p}{2}t}, \quad y_2(t) = t e^{-\frac{p}{2}t}$$

To solve an initial value problem, try

$$y(t) = C_1 y_1(t) + C_2 y_2(t)$$

and determine C_1, C_2 by initial condition.

Ex Solve

$$\frac{d^2 y}{dt^2} + 2 \frac{dy}{dt} + 2y = 0, \quad y(0) = 1, \quad y'(0) = 2$$

$$s^2 + 2s + 2 = 0$$

$$s = \frac{-2 \pm \sqrt{2^2 - 4 \cdot 1 \cdot 2}}{2} = \frac{-2 \pm \sqrt{-4}}{2} = \frac{-2 \pm 2i}{2} = -1 \pm i$$

coeff = -1 coeff = 1

$$\Rightarrow y_1(t) = e^{-t} \cos t$$

$$y_2(t) = e^{-t} \sin t$$

$$y(t) = C_1 e^{-t} \cos t + C_2 e^{-t} \sin t$$

$$y'(t) = C_1 (-e^{-t} \cos t - e^{-t} \sin t) + C_2 (-e^{-t} \sin t + e^{-t} \cos t)$$

$$y(0) = C_1 \quad y'(0) = -C_1 + C_2$$

$$\text{initial condition} \Rightarrow \begin{cases} C_1 = 1 \\ -C_1 + C_2 = 2 \end{cases} \Rightarrow C_2 = 3$$

$$\Rightarrow y(t) = e^{-t} \cos t + 3 e^{-t} \sin t .$$

Ex Solve

$$\frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 4y = 0, \quad y(0) = 1, \quad y'(0) = 2$$

$$s^2 + 4s + 4 = 0 \quad (s+2)^2 = 0 \quad s = -2$$

$$y_1(t) = e^{-2t} \quad y_2(t) = t e^{-2t}$$

$$y(t) = C_1 e^{-2t} + C_2 t e^{-2t}$$

$$y'(t) = -2C_1 e^{-2t} + C_2 (e^{-2t} - 2t e^{-2t})$$

$$y(0) = C_1 \quad y'(0) = -2C_1 + C_2$$

$$\text{initial condition} \Rightarrow \begin{cases} C_1 = 1 \\ -2C_1 + C_2 = 2 \end{cases} \Rightarrow C_2 = 4$$

$$\Rightarrow y(t) = e^{-2t} + 4t e^{-2t}$$

2.6 Existence and uniqueness of systems

General system of first order DEs for $y_1(t), \dots, y_n(t)$

$$\begin{cases} \frac{dy_1}{dt} = f_1(t, y_1, \dots, y_n) \\ \vdots \\ \frac{dy_n}{dt} = f_n(t, y_1, \dots, y_n) \end{cases} \quad \text{initial condition} \quad \begin{cases} y_1(t_0) = y_{1,0} \\ \vdots \\ y_n(t_0) = y_{n,0} \end{cases}$$

$$\vec{Y}(t) = \begin{pmatrix} y_1(t) \\ \vdots \\ y_n(t) \end{pmatrix} \quad \vec{F}(t, \vec{Y}) = \begin{pmatrix} f_1(t, y_1, \dots, y_n) \\ \vdots \\ f_n(t, y_1, \dots, y_n) \end{pmatrix}$$

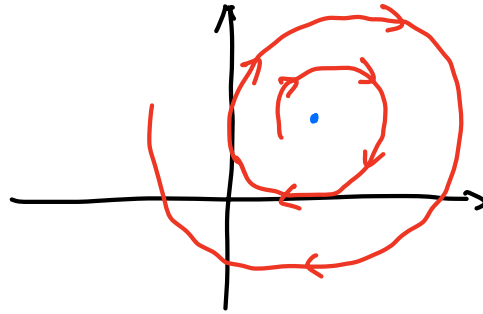
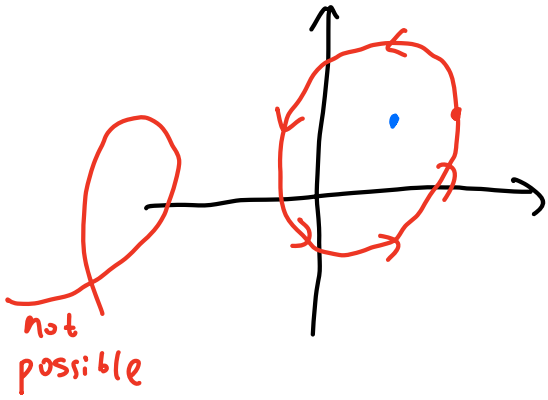
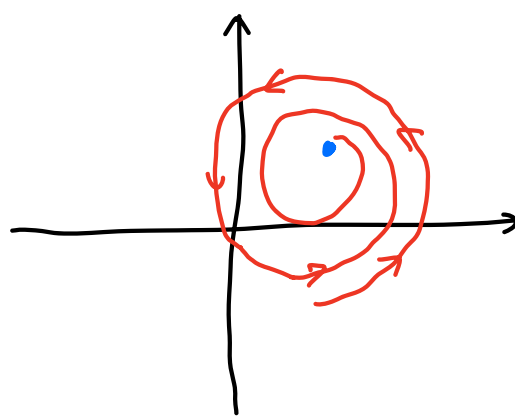
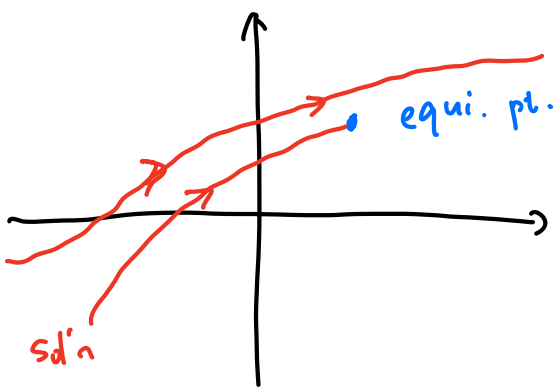
$$\vec{Y}_0 = \begin{pmatrix} y_{1,0} \\ \vdots \\ y_{n,0} \end{pmatrix}$$

$$\frac{d\vec{Y}}{dt} = \vec{F}(t, \vec{Y}), \quad \text{initial condition: } \vec{Y}(t_0) = \vec{Y}_0 \quad (1)$$

Thm If $\vec{F}(t, \vec{Y})$ and $\frac{\partial \vec{F}}{\partial \vec{Y}}$ are continuous, then there exists
 $\hookrightarrow \frac{\partial f_i}{\partial y_j}$ where $i, j = 1, \dots, n$

$\varepsilon > 0$ such that the initial value problem (1) has a unique sol'n $\vec{Y}(t)$ defined on $(t_0 - \varepsilon, t_0 + \varepsilon)$.

- For autonomous systems, sol'n curves cannot intersect (w/ each other or w/ itself).



• For a p -th order DE for $y(t)$

$$\frac{d^p y}{dt^p} = f\left(t, y, \frac{dy}{dt}, \dots, \frac{d^{p-1}y}{dt^{p-1}}\right)$$

Let $y_1(t) = y(t)$

$y_2(t) = \frac{dy}{dt}$

$y_3(t) = \frac{d^2 y}{dt^2}$

⋮

$y_{p-1}(t) = \frac{d^{p-2} y}{dt^{p-2}}$

$y_p(t) = \frac{d^{p-1} y}{dt^{p-1}}$

$$\Rightarrow \begin{cases} \frac{dy_1}{dt} = y_2 \\ \frac{dy_2}{dt} = y_3 \\ \vdots \\ \frac{dy_{p-1}}{dt} = y_p \\ \frac{dy_p}{dt} = f(t, y_1, y_2, \dots, y_p) \end{cases}$$

Initial values $\begin{cases} y_1(t_0) = y_{1,0} \\ y_2(t_0) = y_{2,0} \\ \vdots \\ y_p(t_0) = y_{p,0} \end{cases}$

\Rightarrow for p -th order DE, one needs initial values $\begin{cases} y(t_0) = y_{1,0} \\ \frac{dy}{dt}(t_0) = y_{2,0} \\ \vdots \\ \frac{d^{p-1}y}{dt^{p-1}}(t_0) = y_{p,0} \end{cases}$