

1.8 (continued)

A first order linear DE:

$$\frac{dy}{dt} = a(t)y + b(t) \quad \text{--- -- -- -- -- (1)}$$

A first order linear DE is homogeneous if it has the form

$$\frac{dy}{dt} = a(t)y \quad \text{--- -- -- -- -- (2)}$$

Thm (linear principle) If $y_1(t)$, $y_2(t)$ are sol'n's to (2),

and k is any constant, then

• $y_1(t) + y_2(t)$ is also a sol'n to (2)

• $ky_1(t)$ is also a sol'n to (2)

(That is, all sol'n's to (2) form a vector space).

↳ Proof of item 1

$$\frac{dy_1}{dt} = a(t)y_1$$

$$\frac{dy_2}{dt} = a(t)y_2$$

$$\Rightarrow \frac{d}{dt}(y_1 + y_2) = a(t)y_1 + a(t)y_2 = a(t)(y_1 + y_2)$$

$$\Rightarrow y_1 + y_2 \text{ is a sol'n to (2).}$$

Thm Suppose $y_p(t)$ is a particular sol'n to (1). Then

any sol'n to (1) has the form

$$y(t) = y_p(t) + y_h(t) \quad \text{--- -- -- -- -- (3)}$$

where $y_h(t)$ is any sol'n to (2).

In principle, to get general sol'n to (1), we can proceed as

- find a particular sol'n $y_p(t)$ to (1)
- find general sol'n $y_h(t)$ to (2)

Proof • Prove that (3) is a sol'n to (1)

$$\begin{aligned}\frac{d}{dt}(y_p(t) + y_h(t)) &= \frac{dy_p}{dt} + \frac{dy_h}{dt} \\ &= a(t)y_p + b(t) + a(t)y_h \\ &= a(t)(y_p + y_h) + b(t)\end{aligned}$$

$\Rightarrow y_p + y_h$ is a sol'n to (1)

• Prove that any sol'n to (1) has the form (3)

Suppose $y(t)$ is a sol'n to (1). Write

$$y(t) = y_p(t) + (y(t) - y_p(t))$$

$$\begin{aligned}\frac{d}{dt}(y(t) - y_p(t)) &= \frac{dy}{dt} - \frac{dy_p}{dt} \\ &= (a(t)y + b(t)) - (a(t)y_p + b(t)) \\ &= a(t)(y - y_p)\end{aligned}$$

$\Rightarrow y - y_p$ is a sol'n to (2)

Last time: $\frac{dy}{dt} + \frac{1}{t}y = t^2$

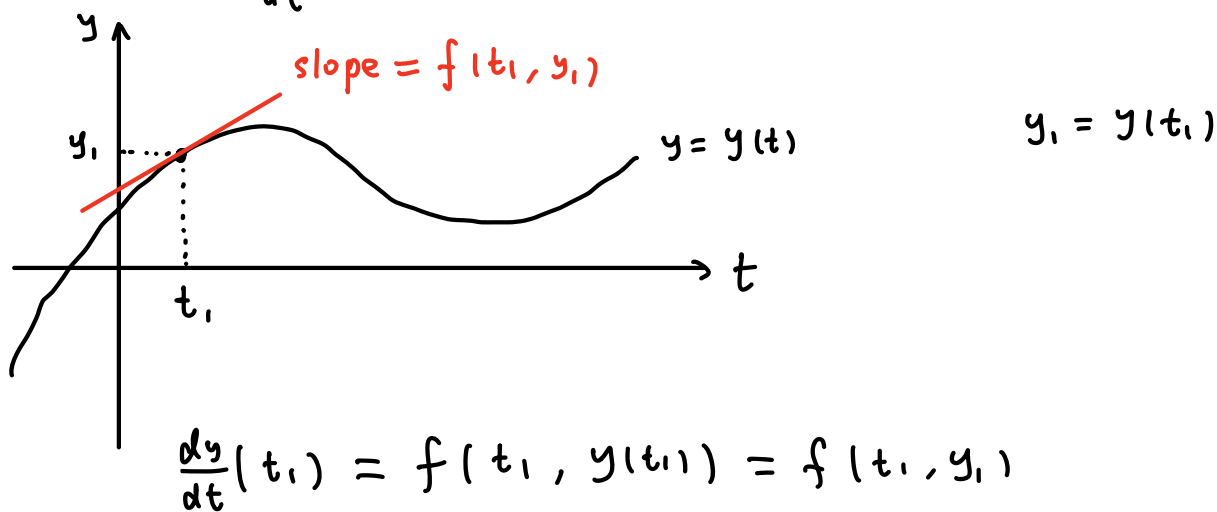
General sol'n $y = \underbrace{\frac{1}{4}t^3}_{y_p(t)} + \underbrace{\frac{C}{t}}_{y_h(t)}$

homogeneous eq. $\frac{dy}{dt} + \frac{1}{t}y = 0$

$$\frac{d}{dt}\left(\frac{C}{t}\right) + \frac{1}{t}\left(\frac{C}{t}\right) = C \cdot \left(-\frac{1}{t^2}\right) + \frac{C}{t^2} = 0$$

1.3 Slope fields

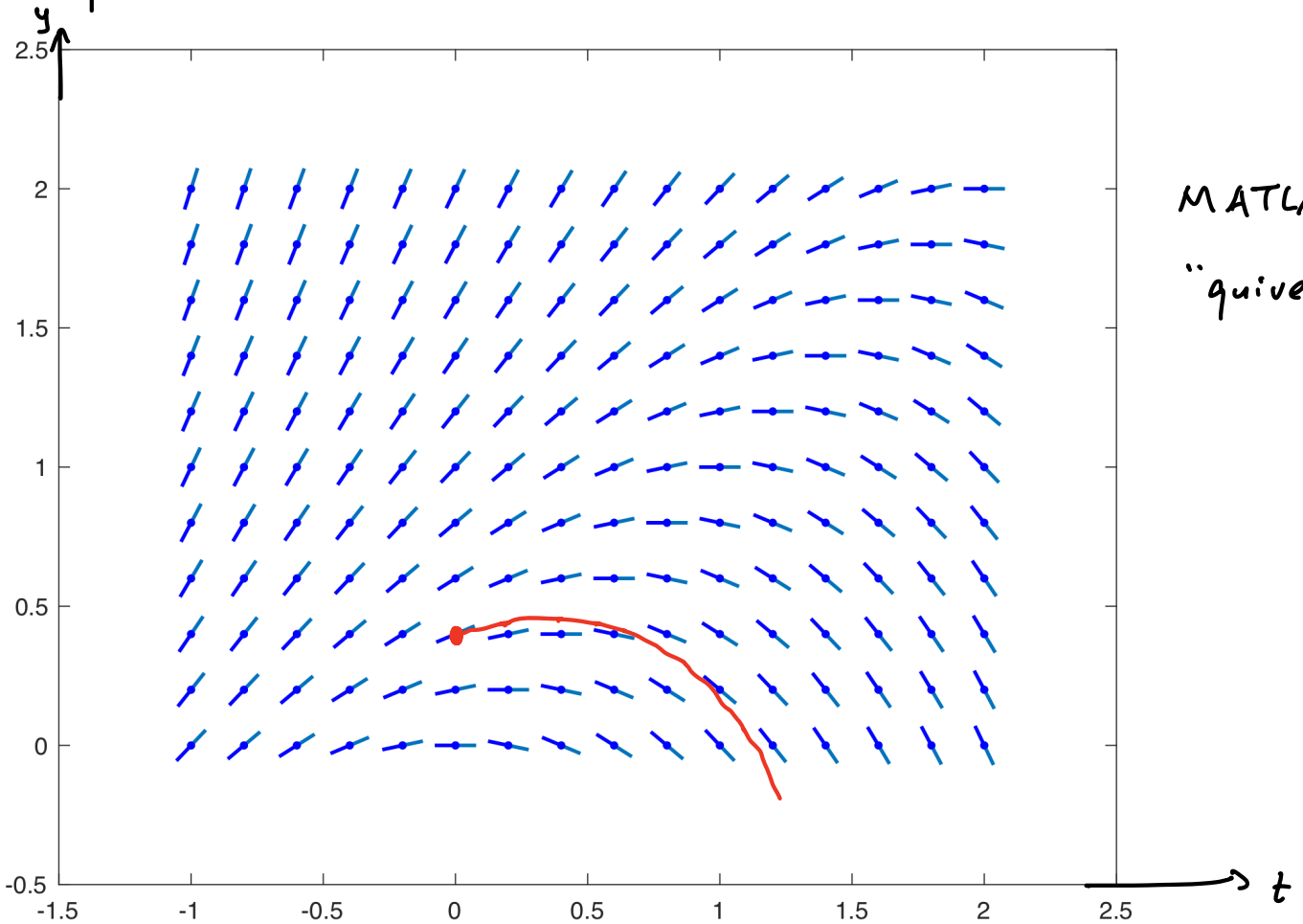
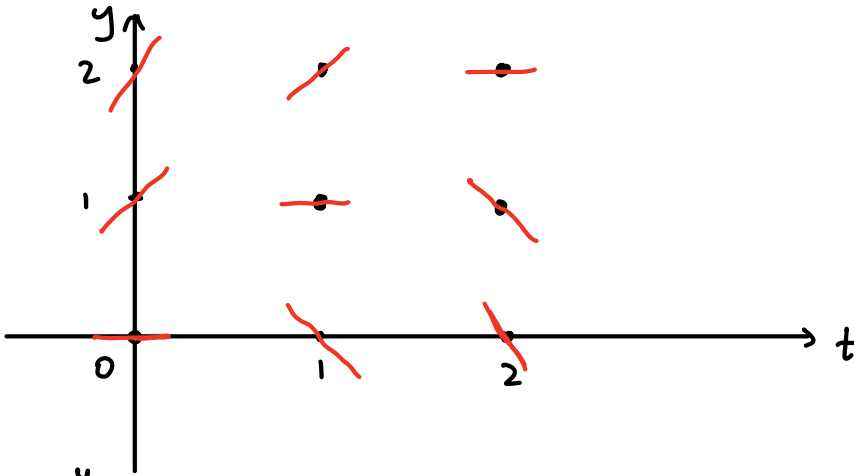
Consider $\frac{dy}{dt} = f(t, y)$. Let $y(t)$ be a sol'n.



Slope field of $f(t, y)$: At each point (t, y) , draw a small line segment w/ slope $f(t, y)$.

Any sol'n to $\frac{dy}{dt} = f(t, y)$ is tangent to these segments whenever it passes the corresponding point (t, y)

$$\underline{\text{Ex}} \quad \frac{dy}{dt} = y - t$$



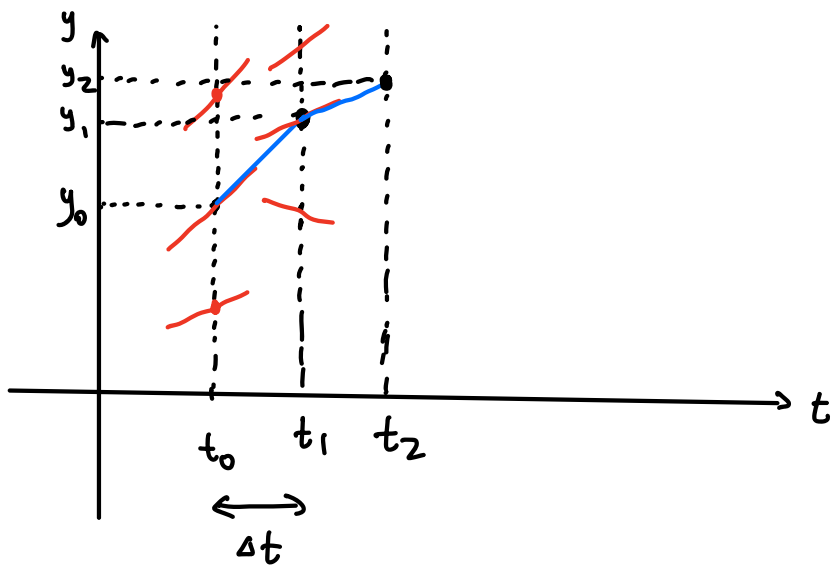
MATLAB
"quiver"

1.4 Euler's method

To solve the initial value problem

$$\frac{dy}{dt} = f(t, y), \quad y(t_0) = y_0$$

numerically, follow the slope field:



$$y_1 = y_0 + \Delta t \cdot f(t_0, y_0)$$

$$y_2 = y_1 + \Delta t \cdot f(t_1, y_1)$$

⋮

$$t_k = t_0 + k \Delta t$$

$$k = 0, 1, 2, \dots$$

$$y_{k+1} = y_k + \Delta t \cdot f(t_k, y_k)$$

Euler's method

y_k is an approximation of $y(t_k)$

Ex Use Euler's method w/ $\Delta t = 0.5$ to solve

$$\frac{dy}{dt} = \underbrace{y - t}_{f(t, y)}, \quad y(0) = 0.4$$

to approximate $y(1)$

$$\# \text{ of time steps} = \frac{1 - 0}{0.5} = 2$$

$$t_0 = 0, \quad t_1 = 0.5, \quad t_2 = 1$$

$$y_1 = y_0 + \Delta t \cdot f(t_0, y_0) = 0.4 + 0.5 \cdot f(0, 0.4)$$

$$= 0.4 + 0.5 \cdot (0.4 - 0) = 0.6$$

$$y_2 = y_1 + \Delta t \cdot f(t_1, y_1) = 0.6 + 0.5 \cdot f(0.5, 0.6)$$

$$= 0.6 + 0.5 \cdot (0.6 - 0.5) = \boxed{0.65}$$

Error of Euler's method

- For a fixed time interval, smaller Δt gives better approximation (although requires more calculation).

The error of the Euler's method is about proportional to Δt .

- For a fixed Δt , if one runs the method for a long time, the error usually grows exponentially in time.