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## 1.1 Modeling via differential equations

Consider a quantity which changes w/ time. The rate of change (derivatives) may depend on its current value.

Ex 1 Rat population in Athens  $P(t)$ .

Its rate of change (growth) is proportional to the current population. (say, coefficient is  $k > 0$ )

$$\leadsto \frac{dP}{dt} = kP$$

General solution:  $P(t) = Ce^{kt}$  (for any constant  $C$ )

$$\frac{d}{dt} \underbrace{(Ce^{kt})}_P = Ce^{kt} \cdot k = kP$$

The function  $P(t)$  can be determined if we know its initial value  $P(t_0) = P_0$

$$P_0 = Ce^{kt_0} \quad C = P_0 e^{-kt_0}$$

$\leadsto$  the unique sol<sup>n</sup> satisfying the initial condition is

$$P(t) = P_0 e^{-kt_0} e^{kt} = P_0 e^{k(t-t_0)} \quad \text{"particular solution"}$$

If  $P_0 > 0$ , then the population grows exponentially in time.

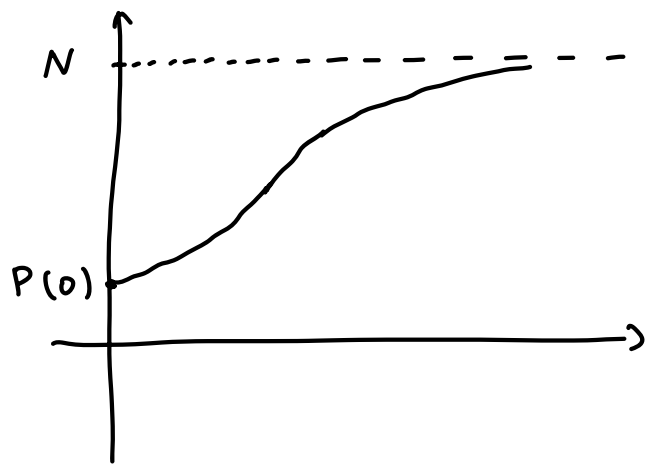
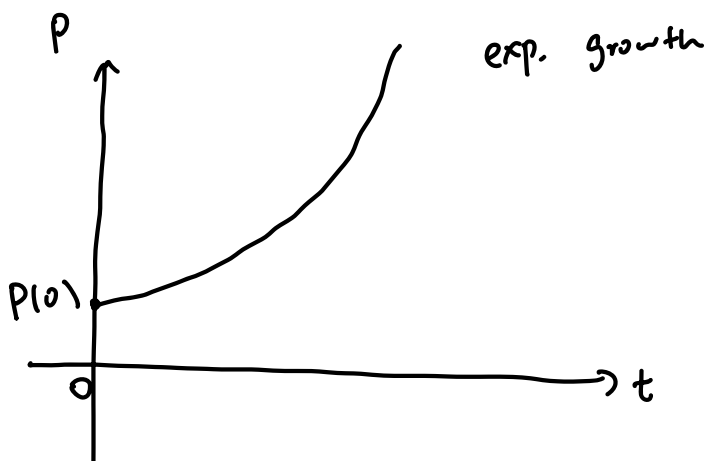
Ex 2 An improved model: logistic population model.

Population growth is restricted by the environment.

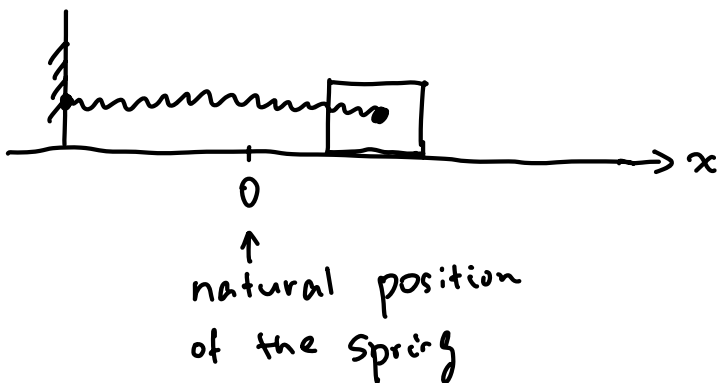
Constant parameter  $N$ : carrying capacity of the environment.

$$\frac{dP}{dt} = kP \left(1 - \frac{P}{N}\right)$$

- when  $P$  is much less than  $N$ , then  $\frac{dP}{dt} \approx kP$   
(similar to exponential growth)
- when  $P > N$ , then  $\frac{dP}{dt} < 0 \rightarrow$  population decays.



Ex 3 Harmonic oscillator



$x(t)$ : position of the block

$m$ : mass

$k$ : spring constant

Hooke's law: magnitude of force on block is  $kx$

Newton's 2nd law:

$$m \frac{d^2 x}{dt^2} = -kx$$

↑  
acceleration

"a second order differential eq."

Ex 4 A chemical reaction  $A + 2B \rightarrow 4D$

$c_A(t)$ ,  $c_B(t)$ ,  $c_D(t)$ : concentration of chemicals.

The reaction rate is proportional to  $c_A c_B^2$  (say,  $k_{\text{eff}}$  is  $k$ )

$$\begin{cases} \frac{dc_A}{dt} = -k c_A c_B^2 \\ \frac{dc_B}{dt} = -2k c_A c_B^2 \\ \frac{dc_D}{dt} = 4k c_A c_B^2 \end{cases}$$

"a system of differential eq.s"

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- Generally, an ordinary differential equation is an equation containing some unknown functions and their (possibly high order) derivatives.
  - It is p-th order if the highest order derivative involved has order  $p$ .
  - A (particular) solution to a DE is a formula of unknown functions so that the DE is satisfied.
  - The general solution to a DE is a formula of unknown functions (involving parameters), which describe all sol'ns to the DE

General form of a first order DE w/ one unknown function  $y(t)$

$$\frac{dy}{dt} = f(t, y) \quad \dots \quad (*)$$

Initial value problem:  $(*)$  w/ initial condition  $y(t_0) = y_0$

"Usually" such an initial value problem has a unique sol'n.

Ex Verify that  $x(t) = \cos(\sqrt{\frac{k}{m}} t)$  is a sol'n to  $m \frac{d^2 x}{dt^2} = -kx$ .

$$\frac{dx}{dt} = -\sqrt{\frac{k}{m}} \sin(\sqrt{\frac{k}{m}} t)$$

$$\frac{d^2 x}{dt^2} = -\sqrt{\frac{k}{m}} \cdot \sqrt{\frac{k}{m}} \cos(\sqrt{\frac{k}{m}} t) = -\frac{k}{m} \cos(\sqrt{\frac{k}{m}} t)$$

$$m \frac{d^2 x}{dt^2} = -k \cos(\sqrt{\frac{k}{m}} t), \quad -kx = -k \cos(\sqrt{\frac{k}{m}} t) \quad \text{are equal.}$$

How to study DEs?

- Find explicit sol'n's. (only possible for some special cases).
- Numerical sol'n's: get approximations of sol'n's via algorithms.
- Qualitative analysis  
( is the sol'n increasing/decreasing ?  
concave up/down ?  
behavior of sol'n as  $t \rightarrow \infty$  ? )