

## 4.2 The LU and Cholesky factorizations

Recall: Gaussian elimination for linear system of equations

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ \dots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{cases}$$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

Issue: one often needs to solve  $A\vec{x} = \vec{b}$  w/ one fixed  $A$  and many different  $\vec{b}$ .

Notice: Coeffs in G.e. only depends on  $A$   
 $\Rightarrow$  do G.e. for  $A$  and store info.

$$A\vec{x} = \vec{b}$$

$$\begin{pmatrix} \boxed{a_{11}} & a_{12} & \dots & a_{1n} & \vdots & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & \vdots & b_2 \\ \vdots & \vdots & & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} & \vdots & b_n \end{pmatrix} \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \vdots \\ \textcircled{n} \end{matrix}$$

$A = A^{(1)}$

Suppose  $a_{11} \neq 0$ . Then, row operations:

$$\textcircled{i} \rightarrow \textcircled{i} - \frac{a_{i1}}{a_{11}} \textcircled{1} \quad i = 2, \dots, n$$

$$\begin{pmatrix} a_{11}^{(2)} & a_{12}^{(2)} & \dots & a_{1n}^{(2)} & \vdots & b_1^{(2)} \\ 0 & \boxed{a_{22}^{(2)}} & \dots & a_{2n}^{(2)} & \vdots & b_2^{(2)} \\ \vdots & \vdots & & \vdots & \vdots & \vdots \\ 0 & a_{n2}^{(2)} & \dots & a_{nn}^{(2)} & \vdots & b_n^{(2)} \end{pmatrix} \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \vdots \\ \textcircled{n} \end{matrix}$$

$A^{(2)}$

$$A^{(2)} = M^{(1)} A^{(1)}$$

$$M^{(1)} = \begin{pmatrix} 1 & & & & & \\ -\frac{a_{21}}{a_{11}} & 1 & & & & \\ \vdots & & \ddots & & & \\ -\frac{a_{n1}}{a_{11}} & & & 1 & & \end{pmatrix}$$

Suppose  $a_{22}^{(2)} \neq 0$ . Then

$(i) \rightsquigarrow (i) - \frac{a_{i2}^{(2)}}{a_{22}^{(2)}} (2) \quad i = 3, \dots, n$

(total  $n-1$  steps)

$$\left( \begin{array}{cccc|c}
 a_{11}^{(n)} & a_{12}^{(n)} & \dots & a_{1n}^{(n)} & b_1^{(n)} \\
 & a_{22}^{(n)} & \dots & a_{2n}^{(n)} & b_2^{(n)} \\
 & & \ddots & \vdots & \vdots \\
 & & & a_{nn}^{(n)} & b_n^{(n)}
 \end{array} \right)$$

(upper-triangular form)

$$A^{(3)} = M^{(2)} A^{(2)}$$

$$M^{(2)} = \begin{pmatrix} 1 & & & & \\ & 1 & & & \\ & -\frac{a_{32}^{(2)}}{a_{22}^{(2)}} & & & \\ & \vdots & & & \\ & & & 1 & \\ & & & & \ddots \\ & & & & & 1 \end{pmatrix}$$

$$U := A^{(n)} = M^{(n-1)} A^{(n-1)}$$

Backward substitution:

$$x_n = \frac{b_n^{(n)}}{a_{nn}^{(n)}}$$

$$x_{n-1} = \frac{1}{a_{n-1,n-1}^{(n)}} \left( b_{n-1}^{(n)} - a_{n-1,n}^{(n)} x_n \right)$$

⋮

$$x_1 = \frac{1}{a_{11}^{(n)}} \left( b_1^{(n)} - a_{12}^{(n)} x_2 - \dots - a_{1n}^{(n)} x_n \right)$$

$$U = M^{(n-1)} \dots M^{(2)} M^{(1)} A$$

$$A = \underbrace{(M^{(1)})^{-1} (M^{(2)})^{-1} \dots (M^{(n-1)})^{-1}}_L U$$

$L$  (lower-triangular w/ diagonal entries 1)

$$\begin{pmatrix} 1 & & & \\ \vdots & \ddots & & \\ & & 1 & \\ & & & \ddots & \\ & & & & 1 \end{pmatrix} \begin{pmatrix} 1 & & & \\ \vdots & \ddots & & \\ & & 1 & \\ & & & \ddots & \\ & & & & 1 \end{pmatrix} \dots$$

$$L = \begin{pmatrix} 1 & & & & \\ \frac{a_{21}}{a_{11}} & 1 & & & \\ \frac{a_{31}}{a_{11}} & \frac{a_{32}^{(2)}}{a_{22}^{(2)}} & 1 & & \\ \vdots & \vdots & & \ddots & \\ \frac{a_{n1}}{a_{11}} & \frac{a_{n2}^{(2)}}{a_{22}^{(2)}} & \dots & \dots & \frac{a_{n,n-1}^{(n-1)}}{a_{n-1,n-1}^{(n-1)}} & 1 \end{pmatrix}$$

Def For an  $n \times n$  matrix  $A$ , an LU-decomposition is  $A = LU$  (LU-factorization) w/  $L$  lower-triangular and  $U$  upper-triangular.

(usually one requires  $A$  nonsingular, so  $L, U$  nonsingular, i.e. diagonal entries of  $L, U$  are nonzero).

Suppose we have an LU-decomposition of  $A$ . Then, to solve  $A\vec{x} = \vec{b}$ ,

$$\underbrace{L U}_{\vec{y}} \vec{x} = \vec{b} \quad \left\{ \begin{array}{l} L \vec{y} = \vec{b} \\ U \vec{x} = \vec{y} \end{array} \right.$$

$$\begin{pmatrix} l_{11} & & & \\ l_{12} & l_{22} & & \\ \vdots & & \ddots & \\ l_{1n} & l_{2n} & \dots & l_{nn} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

forward substitution

$$y_1 = \frac{b_1}{l_{11}}$$

$$y_2 = \frac{1}{l_{22}} (b_2 - l_{12} y_1)$$

...

$$y_n = \frac{1}{l_{nn}} (b_n - l_{1n} y_1 - \dots - l_{n-1,n} y_{n-1})$$

$$U \vec{x} = \vec{y}$$

can be solved by backward substitution.

• Computational cost of G.e. / LU-decomp.

LU-decomp. :

Step 1:  $(n-1) + (n-1)^2 \approx n^2$

Step 2:  $(n-1)^2$

⋮

Step  $n-1$ :  $1^2$

$$1^2 + 2^2 + \dots + n^2 \approx \frac{1}{3} n^3$$

backward / forward substitution :

$$1 + 2 + \dots + n \approx \frac{1}{2} n^2$$

⇒ If we do LU-decomp. for  $A$  and solve  $A\vec{x} = \vec{b}$   $m$  times, then

$$\text{total cost} = \frac{1}{3} n^3 + m \cdot n^2$$

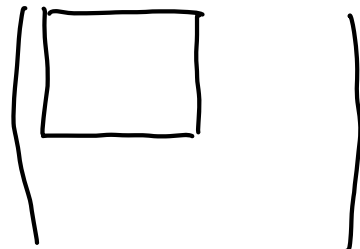
Thm If all leading minors of  $A$  are nonsingular, then  $A$  has an LU-decomposition.

$$\begin{pmatrix} a_{11} & \dots & a_{1k} \\ \vdots & & \vdots \\ a_{ki} & \dots & a_{kk} \end{pmatrix} \quad k=1, \dots, n$$

Proof

The property "all leading minors are nonsingular" is preserved by Gaussian elimination.

⇒ before Step  $k$ ,



Since the  $k$ -th leading minor here is upper-triangular and nonsingular, we have  $a_{kk}^{(k)} \neq 0$ .

$\Rightarrow$  G.e. can always be done, giving LU-decomp.

Thm LU-decomp. is unique once the diagonal entries of  $L$  is given.

$$LU = (LD)D^{-1}U$$

Proof Suppose  $A = LU = \tilde{L}\tilde{U}$  w/  $L, \tilde{L}$  having the same diagonal.

$$\Rightarrow \underbrace{\tilde{L}^{-1}L}_{\text{lower-triangular}} = \underbrace{\tilde{U}U^{-1}}_{\text{upper-triangular}} \Rightarrow \tilde{L}^{-1}L \text{ is diagonal.}$$

$$L = \begin{pmatrix} l_{11} & & \\ & \ddots & \\ & & l_{nn} \end{pmatrix} \quad \tilde{L} = \begin{pmatrix} \tilde{l}_{11} & & \\ & \ddots & \\ & & \tilde{l}_{nn} \end{pmatrix} \quad \tilde{L}^{-1} = \begin{pmatrix} \tilde{l}_{11}^{-1} & & \\ & \ddots & \\ & & \tilde{l}_{nn}^{-1} \end{pmatrix}$$

$$\tilde{L}^{-1}L = \begin{pmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{pmatrix} = I \Rightarrow \tilde{L} = L, \tilde{U} = U.$$

### LU-decomp for symmetric matrices

Assume  $A$  is symmetric, and has an LU-decomp. w/  $L$  having diagonal entries 1.

$$A = \begin{pmatrix} * & & \\ * & * & \\ & * & * \end{pmatrix}$$

$$A = \boxed{LU} = LD\tilde{U} \quad \text{where } D = \text{diag}\{u_{11}, \dots, u_{nn}\} \text{ and } \tilde{U} \text{ is upper-triangular w/ diag. entries 1}$$

$$D^{-1}U = \begin{pmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{pmatrix} := \tilde{U}$$

$$A^T = A = \underbrace{\tilde{U}^T}_{\text{lower-triangular}} \underbrace{DL^T}_{\text{upper-triangular}}$$

$\Rightarrow$  by uniqueness of LU-decomp.,  $\tilde{U}^T = L$

$$\Rightarrow A = LDL^T$$

Therefore, for sym. matrices, one only needs to store  $L$  and  $D$  for its LU-decomp.

$$\begin{array}{c} \uparrow \\ \frac{1}{2}n(n-1) \\ \uparrow \\ n \end{array}$$

(about half of the cost for general matrix).

• When doing G.e. for sym. matrix,

$$\left( \begin{array}{cccc} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{array} \right)^{\text{Sym}}$$

$$a_{32}^{(2)} = a_{32} - \frac{a_{31}}{a_{11}} a_{12}$$

$$a_{23}^{(2)} = a_{23} - \frac{a_{21}}{a_{11}} a_{13}$$

$$\textcircled{i} \rightsquigarrow \textcircled{i} - \frac{a_{i1}}{a_{11}} \textcircled{1} \quad i = 2, \dots, n$$

$$\left( \begin{array}{cccc} a_{11}^{(2)} & a_{12}^{(2)} & \dots & a_{1n}^{(2)} \\ 0 & a_{22}^{(2)} & \dots & a_{2n}^{(2)} \\ \vdots & \vdots & & \vdots \\ 0 & a_{n2}^{(2)} & \dots & a_{nn}^{(2)} \end{array} \right)^{\text{Sym}}$$

you only need to calculate lower-triangular and diagonal parts for these entries

$\Rightarrow$  Save about half of the computational cost of G.e.